CELLULAR VEHICLE TO EVERYTHING (C-V2X)

TESTING CONNECTED VEHICLES IN THE LAB

Holger Rosier



ROHDE&SCHWARZ

Make ideas real



SIX LEVELS OF DRIVING AUTOMATION

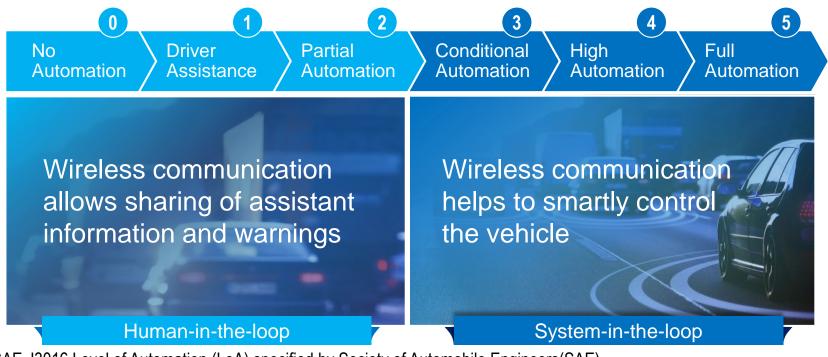
	0	1	2	3	4	5
	No Automation	Driver Assistance	Partial Automation	Conditional Automation	High Automation	Full Automation
Driver	Performs driving control at all times	Performs driving control at all times	Monitors all driving tasks at all times	Must be able to intervene (10s)	Not responsible to intervene	Might not be in the car
System	Doing support	Temporarily performs limited control	Temporarily performs complete control	Performs all tasks in certain scenarios	Performs all tasks in certain scenarios	Responsible at all times
		uman-in-the-loc		Attivate Highway Chaldfear	Cystem-in-the-lo	op

SAE J3016 Level of Automation (LoA) specified by Society of Automobile Engineers(SAE)

Rohde & Schwarz

Testing Connected Vehicles In The Lab

SIX LEVELS OF DRIVING AUTOMATION THE ROLE OF WIRELESS COMMUNICATION



SAE J3016 Level of Automation (LoA) specified by Society of Automobile Engineers(SAE)

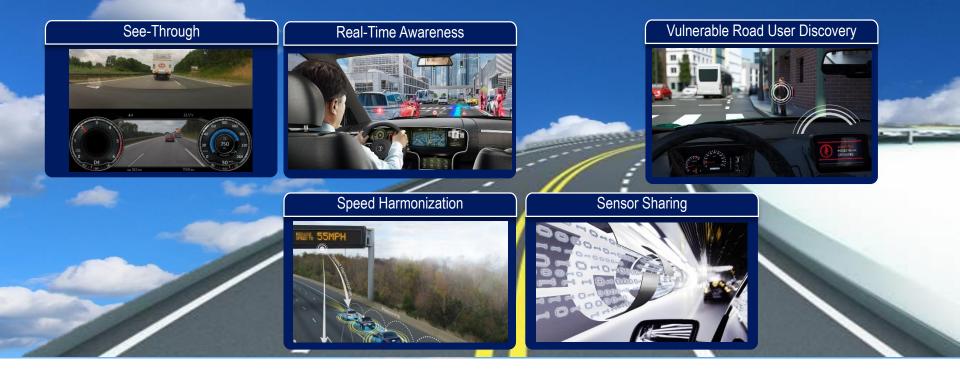
Rohde & Schwarz

Testing Connected Vehicles In The Lab

COOPERATIVE INTELLIGENT TRANSPORTATION SYSTEM (C-ITS) SHORT-TERM DEPLOYMENT



COOPERATIVE INTELLIGENT TRANSPORTATION SYSTEM (C-ITS) MID-TERM DEPLOYMENT



COOPERATIVE INTELLIGENT TRANSPORTATION SYSTEM (C-ITS) LONG-TERM DEPLOYMENT



3GPP LTE-V2X

- 3GPP LTE-V2X Release 14
- V2V published in 2016, V2X in 2017
- Industry term: Cellular V2X (C-V2X)
- Peer-to-peer ad-hoc communication:
 - service continuity, to operate independent of any centralized system
- Backend connectivity through mobile network
- V2V targets 5.9GHz ITS frequency band

IEEE 802.11p

- Amendment to IEEE 802.11 (derived from 11a)
- Ratified in 2010
- EU: Car-to-Everything (C2X), ITS-G5
- U.S: Dedicated Short Range Communication (DSRC), WAVE
- Peer-to-peer ad-hoc communication
- Backend connectivity through Road Side Units
- 5.9GHz ITS frequency band

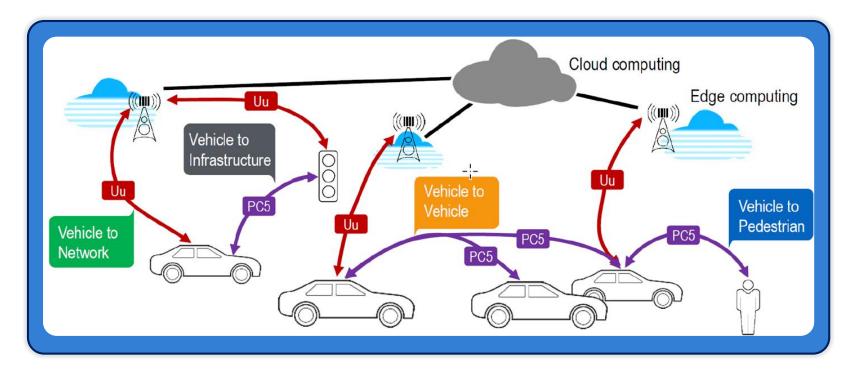


Rohde & Schwarz

UMTS, LTE, 5G



3GPP C-V2X NETWORK ARCHITECTURE



COOPERATIVE INTELLIGENT TRANSPORT SYSTEMS (C-ITS): 3GPP APPROACH



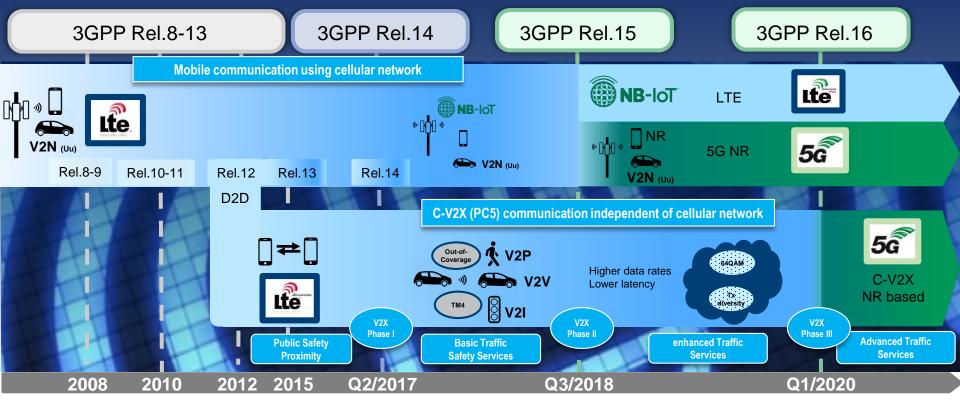
	Application	Safety US	Safety EU	Safety China
ття Асьова	Application	BSM	CAM / DENM	BSM
	Transport	WSMP	BTP	DSMP
V2I:Vehicle to	Network		GeoNet	ADLayer
V2N:Vehicle to Network		Packet Data Convergence		
	MAC	Radio Link Control		
V2P:Vehicle to Pedestrian		Medium Access Control		
	PHY		SC-FDMA	
		USA	EU	China
		1 量		

COOPERATIVE INTELLIGENT TRANSPORT SYSTEMS (C-ITS): 3GPP APPROACH



	•		Application	Safety US	Safety EU	Safety China
BSM Basic Safety	Nessage Message Protocol	LOBA	Application	BSM	CAM / DENM	BSM
Message			Transport	WSMP	BTP	DSMP
SC-FDMA Single Carrier Frequency Division Multiple Access	WAVE Wireless Access in Vehicular Environments	Contraction of the local division of the loc	Network		GeoNet	ADLayer
DENM Decentralized Environment Notification	BTP Basic Transport Protocol	4	MAC	Packet Data Convergence		
Message CAM Cooperative	GeoNet Geo			Radio Link Control		
Awareness Message ADLayer Adaptation	Awareness Message Networking ADLayer Adaptation DSMP DSRC Short			Medium Access Control		
Layer	Layer Message Protocol		PHY	SC-FDMA		
- 10 - 10 - 10		-100		USA	EU	China
		AND NO.		*		

3GPP MOBILE COMMUNICATIONS STANDARD C-V2X ON THE WAY TO 5G NR



Rohde & Schwarz

Testing Connected Vehicles In The Lab

3GPP RELEASE 14: PHASE I LTE-V2X



Collaborative Awareness Extended Visual Horizon

Support direct V2X communication, distributed random and reservation based resource usage to exchange basic traffic safety information

Traffic Warning

Hazardous Information Broadcast transmission service w/o network subscription

Direct PC5 and mobile network Uu communication

Operation in licensed-exempt ITS 5.9GHz frequency spectrum

Semi-persitant scheduling yields spectral efficiency

3GPP RELEASE 15: PHASE II LTE-V2X

Vehicle Platooning Extended Sensors

Support of low latency, high data rate links to exchange data for enhanced automotive applications Transmit diversity

Support of 64QAM for higher data rate

Reduce the max. time between L1 packet arrival and resource selected for transmission from 20 to 10 ms

Advanced Driving Collaborative Perception Aggregation of up to 8 PC5 carriers (TM3 & TM4)

3GPP RELEASE 16: PHASE III 5G NR V2X

High Density Platooning Advanced Sensors Data Sharing

Support broadcast, groupcast, unicast communications for advanced automotive applications

> Remote driving

Flexible numerology

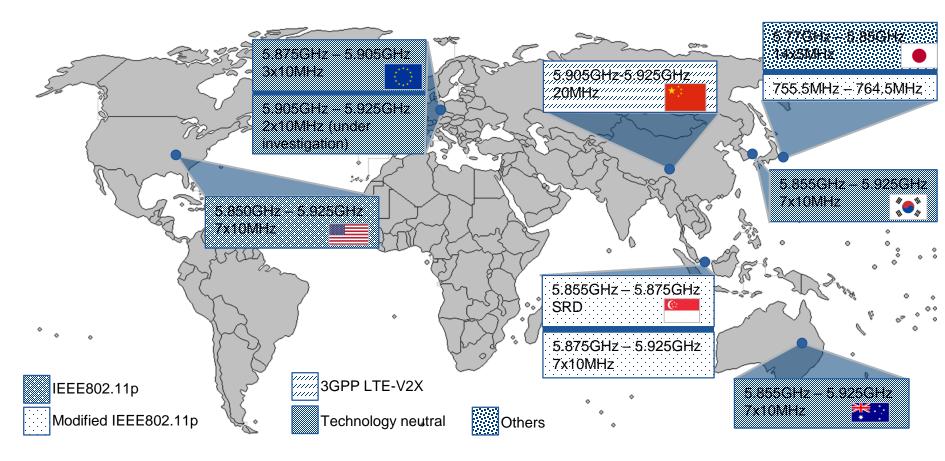
Operates Multiple Input Multiple Output (MIMO) transmission

Distance based Hybrid Automatic Repeat Request (HARQ)

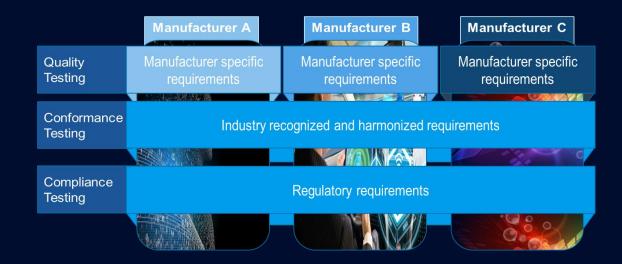
V2X communication in FR1 and FR2

Intention Sharing

V2X – The global view



C-V2X CERTIFICATION



R&S C-V2X TEST SOLUTIONS



Munich | 19-Jun-2018 | Test & Measurement

Rohde & Schwarz delivers 3GPP C-V2X device testing for GCF protocol conformance

Automakers are now well positioned to accelerate cellular vehicle-to-everything (C-V2X) device verification with Global Certification Forum (GCF) protocol conformance testing supported in the R&S CMW500 wideband radio communication tester.



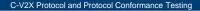
Munich | 18-Feb-2019 | Test & Measurement

Rohde & Schwarz collaborates with Vector to deliver Cellular-V2X end-to-end application layer test solution

Munich | 27-Feb-2018 | Test & Measurement

Rohde & Schwarz demonstrates test capability of 3GPP C-V2X technology in preparation for GCF certification toward commercialization

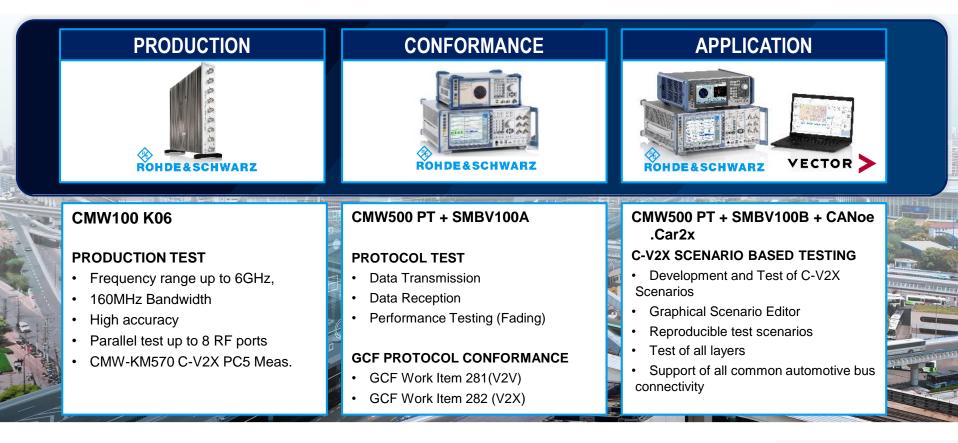
At Mobile World Congress 2018 in Barcelona, Rohde & Schwarz will showcase their CMW500 wideband radio communication tester and a pre-commercial Qualcomm® 9150 C-V2X chipset solution, that implements 3rd Generation Partnership Project (3GPP) Release 14 cellular vehicle-to-everything (C-V2X) direct communications technology. Rohde & Schwarz, working with companies including Qualcomm Technologies, aim to support an official global certification scheme based on 3GPP standardized conformance tests selected by the Global Certification Forum (GCF) in preparation of commercialization.







R&S C-V2X TEST SOLUTIONS



- ► Forward Collision Warning (FCW)
- Intersection Collision Warning (ICW)
- Left Turn Assist (LTA) / Right Turn Assist (RTA)
- Blind Spot Warning (BSW) / Lane Change Warning (LCW)
- Do Not Pass Warning (DNPW)
- Emergency Brake Warning (EBW / Electronic Emergency Brake light (EEBL)
- Abnormal Vehicle Warning (AVW)
- Control Loss Warning (CLW)
- Hazard Location Warning (HLW)

CHINA DAY-1-USE CASES

- Speed Limit Warning (SLW)
- Red Light Violation Warning (RLVW)
- Vulnerable (VRUCW)
- Green Light Optimization Speed (GLOSA)
- In-vehicle signage (IVS)
- Traffic Jam Ahead Warning (TJW)
- Emergency Vehicle Warning (EVW)

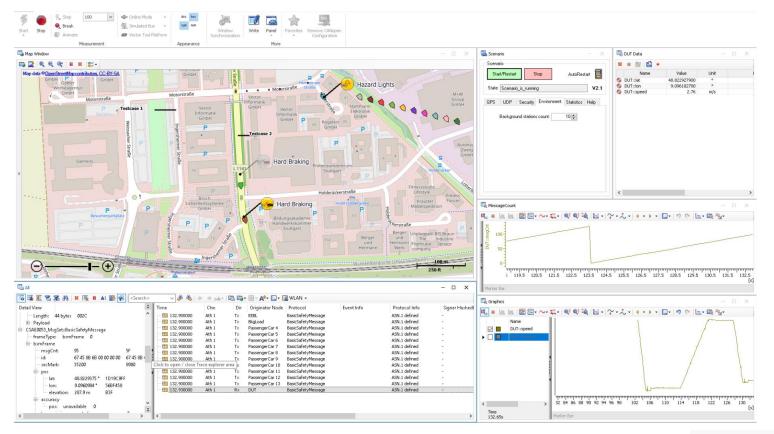
Emergency Electronic Brake Lights

Left Turn Assist





CANOE LOOK AND FEEL

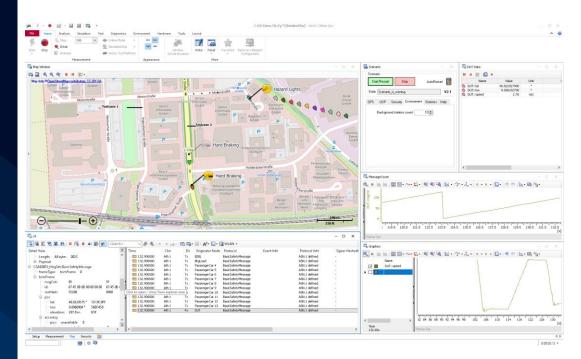


Rohde & Schwarz

Testing Connected Vehicles In The Lab

SIMULATION AND TEST

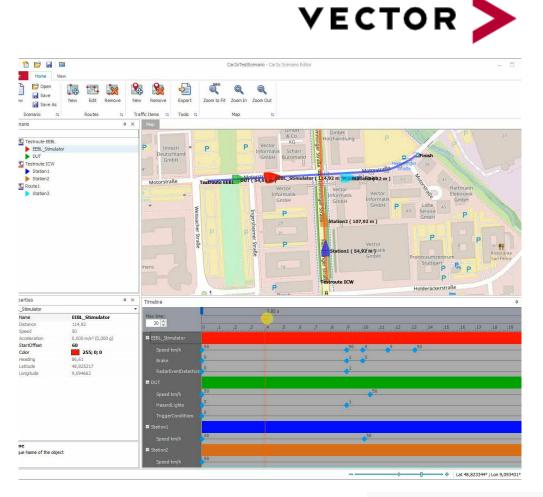
- CANoe imports scenario file
 - <u>Start and stop</u> a scenario
 - <u>Callback functions</u> if keypoints changes or scenario status changes
- Interpretation of ITS relevant protocols
- Support of relevant standards
 - ETSI (EU), WAVE/SAE (US), GB31024 (CN)
 - Security header generation
- Application message support
 - CAM, DENM, Spat/MAP, IVI, BSM,...
- Map window for visualization of the scenario
- Trace/Graphic/Data window for specific measurement and DUT specific data
- Internal programming environment for advanced stimulation and analyzing (CAPL)
- The test solution allows bus connectivity
 - CAN, LIN, FlexRay, Ethernet to analyze results or stimulate the ECU remotely



VECTOR

SCENARIO EDITOR

- GUI for easy and fast traffic scenario configuration
- Multiple virtual cars
- GNSS route definition
- Flexible parameter configuration (speed, signal strength...)
- CAPL interface for fine adjustment of the scenario
- Scenario loaded and played back by CANoe C-V2X communication and waypoints created according to scenario

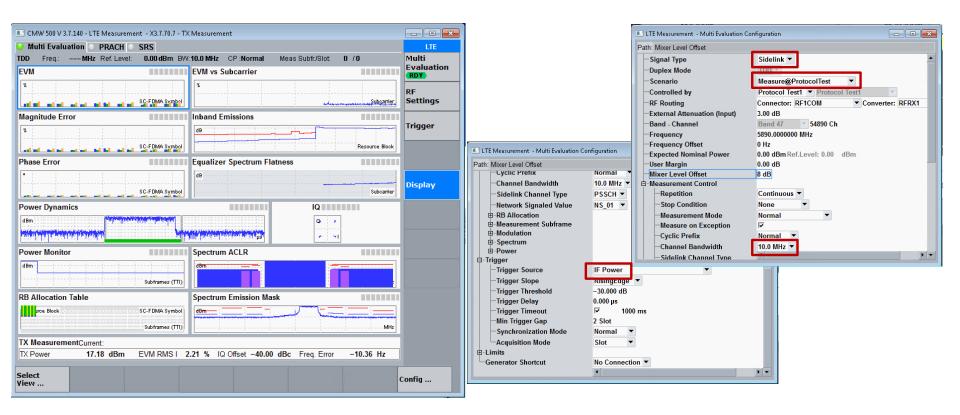


C-V2X SERVING SCENARIO CMW-KAA550

- Abstract the CMW500 and SMBV to "Callbox like operation"
 - Offers a dedicated interface to Vector's CANoe .car2x
 - Features on the interface will grow over time
 - Customer feedback and requirements is required

secution parameters SideLink cell(PC5) LTE cell(Uu)	Pools Config	[INFOR]# XDD Explorer will be started
	Tx Pool (one pool)	[INFOR]# XDD Explorer started correctly. [INFOR]# stored SMBV100 IP address loaded correctly.
SL Band: HD_Band 47 ¥	Communication TM: TM4 -	[INFOR]# stored PoolConfig loaded correctly. [INFOR]# stored Ite-si-parameters loaded correctly.
SL BW: 10Mhz 👻	Sfn Bitmap Type: bs16-r14 👻	[INFOR]# Please proceed as follow : [INFOR]# 1-choose the configuration and click Apply Config btn.
SL earfor: auto	Sfn Bitmap Data: 03ff	[INFOR]# 2-click the connect CANoe btn to start communication with CANoe.
Lano.	Type of subchannet: Non-Adjacent -	
Release 15	Size of subchannel: n4 -	
Tx Diversity: 📗 Enable TxDiv	Num of subchannet n10 -	
CyclicDelay: 20	StartRB-subchannet: 0	
	Rx Pool (one pool)	
	Sfn Bitmap Type: bs16-t14 - Sfn Bitmap Data: 03ff	
	Sfn Bitmap Data: 03ff Type of subchannet: Adjacent-subc 👻	
	Size of subchannel: n5 •	8
	Num of subchannel: n1 +	
	StartRB-subchannet 0	
	use Preconfiguration_r14	
	import from XML	
use (sidelink cell and pools config) defa	ult parameters	
	se SL default config	
	at at default coming	
onnect CANoe	Scenario control Apply Con	a
connect CANoe	Stop scenario	

LTE SIDELINK TX MEASUREMENTS – KM570



REPRODUCIBLE TESTING OF C-V2X IN A LAB ENVIRONMENT 100% REPRODUCIBLE







R&S CMW500 Wideband Communication Tester

- ► C-V2X Signaling LTE Rel-14 TM4 (3GPP Rel.14, PSCCH, PSSCH)
- Multi-technology protocol tester with a layer 1 to layer 3 stack implementation
- Extendable with CMX500 for 5G
- Verify Transmitter characteristics under signaling conditions in combination with KM570 measurements (power, EVM...) and ready to use test packages for transmitter, receiver and performance verification

R&S SMBV100B

- GNSS synchronization and route simulation
- Frequency range from 8 kHz to 3 GHz or 6 GHz
- Signal generation for all major digital communication standard incl. 5G NR, LTE and WLAN
- ► GNSS simulator with GPS, Glonass, Galileo, BeiDou and QZSS/SBAS

VECTOR CANoe .car2x

- ▶ Simulation, analysis and test of C-V2X applications following EU, US and CN standards
- ► Quick and easy scenario design with CANoe .car2x scenario editor

Testing Connected Vehicles In The Lab

COMPANY RESTRICTED

Rohde & Schwarz

QUESTIONS???

Testing Connected Vehicles In The Lab